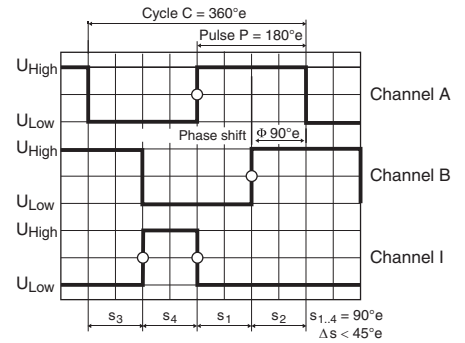
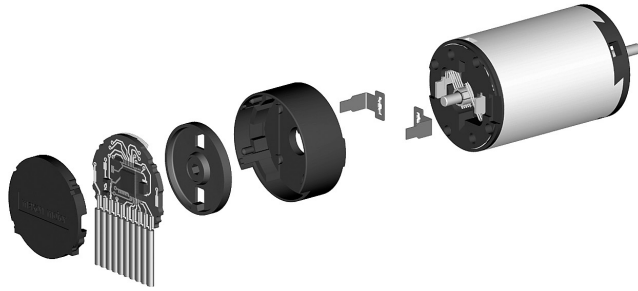


# Encoder MR Type M, 128-512 CPT, 2/3 Channels, with Line Driver

maxon sensor



Direction of rotation cw (definition cw p. 48)

- Stock program
- Standard program
- Special program (on request)

## Order Number

228179	228177	228181	228182	201937	201940
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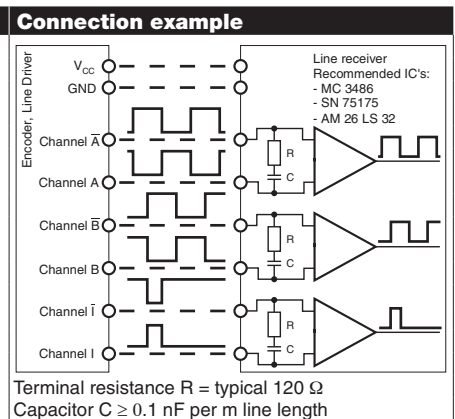
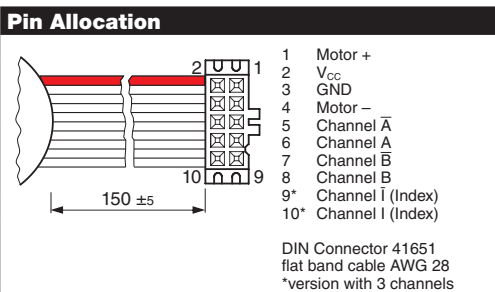
Type							
Counts per turn		128	128	256	256	512	512
Number of channels		2	3	2	3	2	3
Max. operating frequency (kHz)		80	80	160	160	320	320
Max. speed (rpm)		37500	37500	37500	37500	37500	37500



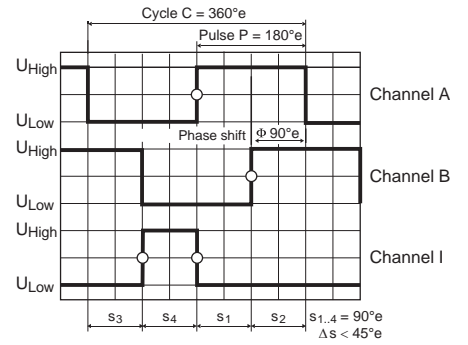
## maxon Modular System

+ Motor	Page	+ Gearhead	Page	+ Brake	Page	Overall length [mm] / ● see Gearhead					
RE 16, 2 W	72					28.0	28.0	28.0	28.0	28.0	28.0
RE 16, 2 W	72	GP 16, 0.06 - 0.18 Nm	214			●	●	●	●	●	●
RE 16, 2 W	72	GP 16, 0.1 - 0.3 Nm	215			●	●	●	●	●	●
RE 16, 3.2 W	74					45.4	45.4	45.4	45.4	45.4	45.4
RE 16, 3.2 W	74	GP 16, 0.06 - 0.18 Nm	214			●	●	●	●	●	●
RE 16, 3.2 W	74	GP 16, 0.1 - 0.3 Nm	215			●	●	●	●	●	●
RE 16, 4.5 W	76					48.4	48.4	48.4	48.4	48.4	48.4
RE 16, 4.5 W	76	GP 16, 0.06 - 0.18 Nm	214			●	●	●	●	●	●
RE 16, 4.5 W	76	GP 16, 0.1 - 0.3 Nm	215			●	●	●	●	●	●
A-max 16	90/92					30.4	30.4	30.4	30.4	30.4	30.4
A-max 16	90/92	GS 16, 0.01 - 0.1 Nm	210-212			●	●	●	●	●	●
A-max 16	90/92	GP 16, 0.06 - 0.18 Nm	214			●	●	●	●	●	●
A-max 16	90/92	GP 16, 0.1 - 0.3 Nm	215			●	●	●	●	●	●
A-max 19, 1.5 W	94					34.0	34.0	34.0	34.0	34.0	34.0
A-max 19, 1.5 W	94	GP 19, 0.1 - 0.3 Nm	217			●	●	●	●	●	●
A-max 19, 1.5 W	94	GP 22, 0.5 - 2.0 Nm	221/222			●	●	●	●	●	●
A-max 19, 1.5 W	94	GS 24, 0.1 Nm	226			●	●	●	●	●	●
A-max 19, 1.5 W	94	GP 22 S	247/248			●	●	●	●	●	●
A-max 19, 2.5 W	96					35.8	35.8	35.8	35.8	35.8	35.8
A-max 19, 2.5 W	96	GP 19, 0.1 - 0.3 Nm	217			●	●	●	●	●	●
A-max 19, 2.5 W	96	GS 20 0.06 - 0.25 Nm	218			●	●	●	●	●	●
A-max 19, 2.5 W	96	GP 22, 0.5 - 2.0 Nm	221/222			●	●	●	●	●	●
A-max 19, 2.5 W	96	GS 24, 0.1 Nm	226			●	●	●	●	●	●
A-max 19, 2.5 W	96	GP 22 S	247/248			●	●	●	●	●	●
A-max 22	98/100					36.9	36.9	36.9	36.9	36.9	36.9
A-max 22	98/100	GP 22, 0.1 - 0.6 Nm	219/220			●	●	●	●	●	●
A-max 22	98/100	GP 22, 0.5 - 2.0 Nm	221/222			●	●	●	●	●	●
A-max 22	98/100	GS 24, 0.1 Nm	226			●	●	●	●	●	●
A-max 22	98/100	GP 22 S	247/248			●	●	●	●	●	●
RE-max 17	120/122					30.4	30.4	30.4	30.4	30.4	30.4
RE-max 17	120/122	GP 16, 0.06 - 0.18 Nm	214			●	●	●	●	●	●
RE-max 17	120/122	GP 16, 0.1 - 0.3 Nm	215			●	●	●	●	●	●

Technical Data	
Supply voltage $V_{CC}$	5 V $\pm$ 5%
Output signal	TTL compatible
Phase shift $\Phi$	$90^\circ \pm 45^\circ e$
Index pulse width	$90^\circ \pm 45^\circ e$
Operating temperature range	-25 ... +85°C
Moment of inertia of code wheel	$\leq 0.09 \text{ gcm}^2$
Output current per channel	max. 5 mA



# Encoder MR Type M, 128-512 CPT, 2/3 Channels, with Line Driver



Direction of rotation cw (definition cw p. 48)

- Stock program
- Standard program
- Special program (on request)

## Order Number

228179	228177	228181	228182	201937	201940
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Type	Counts per turn	128	128	256	256	512	512
	Number of channels	2	3	2	3	2	3
	Max. operating frequency (kHz)	80	80	160	160	320	320
	Max. speed (rpm)	37500	37500	37500	37500	37500	37500

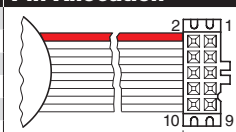
## maxon Modular System

+ Motor	Page	+ Gearhead	Page	+ Brake	Page	Overall length [mm] / ● see Gearhead					
RE-max 21, 3.5 W	124					34.0	34.0	34.0	34.0	34.0	34.0
RE-max 21, 3.5 W	124	GP 22, 0.5 - 2.0 Nm	221/222			●	●	●	●	●	●
RE-max 21, 3.5 W	124	GS 38, 0.1 - 0.6 Nm	236			●	●	●	●	●	●
RE-max 21, 3.5 W	124	GP 22 S	247/248			●	●	●	●	●	●
RE-max 21, 6 W	126					35.8	35.8	35.8	35.8	35.8	35.8
RE-max 21, 6 W	126	GP 22, 0.5 - 2.0 Nm	221/222			●	●	●	●	●	●
RE-max 21, 6 W	126	GS 38, 0.1 - 0.6 Nm	236			●	●	●	●	●	●
RE-max 21, 6 W	126	GP 22 S	247/248			●	●	●	●	●	●
RE-max 24	128/130					36.9	36.9	36.9	36.9	36.9	36.9
RE-max 24	128/130	GP 22, 0.5 - 2.0 Nm	222			●	●	●	●	●	●
RE-max 24	128/130	GS 38, 0.1 - 0.6 Nm	236			●	●	●	●	●	●
RE-max 24	128/130	GP 22 S	247/248			●	●	●	●	●	●
EC 16, 30 W	145					50.7	50.7	50.7	50.7	50.7	50.7
EC 16, 30 W	145	GP 16, 0.1 - 0.3 Nm	215			●	●	●	●	●	●
EC 16, 30 W	145	GP 22, 0.5 - 1.0 Nm	221			●	●	●	●	●	●
EC 16, 60 W	147					66.7	66.7	66.7	66.7	66.7	66.7
EC 16, 60 W	147	GP 22, 0.5 - 1.0 Nm	221			●	●	●	●	●	●
EC 16, 60 W	147	GP 22 S	247/248			●	●	●	●	●	●
EC 16, 60 W	147	GP 22, 0.5 - 2.0 Nm	223			●	●	●	●	●	●
EC 22, 40 W	149					50.5	50.5	50.5	50.5	50.5	50.5
EC 22, 40 W	149	GP 22, 0.5 - 3.4 Nm	223/224			●	●	●	●	●	●
EC 22, 40 W	149	GP 22 S	247/248			●	●	●	●	●	●
EC 22, 100 W	151					68.7	68.7	68.7	68.7	68.7	68.7
EC 22, 100 W	151	GP 22, 0.5 - 3.4 Nm	223/224			●	●	●	●	●	●
EC 22, 100 W	151	GP 22 S	247/248			●	●	●	●	●	●
EC-max 16, 5 W	161					31.3	31.3	31.3	31.3	31.3	31.3
EC-max 16, 5 W	161	GP 16, 0.1 - 0.3 Nm	215			●	●	●	●	●	●
EC-max 16, 8 W	163					43.3	43.3	43.3	43.3	43.3	43.3
EC-max 16, 8 W	163	GP 22, 0.5 - 2.0 Nm	223			●	●	●	●	●	●
EC-max 16, 8 W	163	GP 22 S	247/248			●	●	●	●	●	●
EC-max 22, 12 W	164					41.7	41.7	41.7	41.7	41.7	41.7
EC-max 22, 12 W	164	GP 22, 0.5 - 2.0 Nm	223/224			●	●	●	●	●	●
EC-max 22, 12 W	164	KD 32, 1.0 - 4.5 Nm	235			●	●	●	●	●	●
EC-max 22, 12 W	164	GP 22 S	247/248			●	●	●	●	●	●
EC-max 22, 25 W	165					58.2	58.2	58.2	58.2	58.2	58.2
EC-max 22, 25 W	165	GP 22, 2.0 - 3.4	224			●	●	●	●	●	●
EC-max 22, 25 W	165	GP 32, 1 - 6 Nm	233			●	●	●	●	●	●
EC-max 22, 25 W	165	GP 32 S	247/248			●	●	●	●	●	●

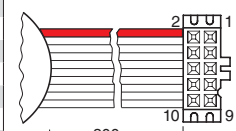
## Technical Data

Supply voltage $V_{CC}$	5 V $\pm$ 5%
Output signal	TTL compatible
Phase shift $\Phi$	90°e $\pm$ 45°e
Index pulse width	90°e $\pm$ 45°e
Operating temperature range	-25 ... +85°C
Moment of inertia of code wheel	$\leq$ 0.09 gcm <sup>2</sup>
Output current per channel	max. 5 mA

## Pin Allocation



MR Encoder EC-max 16 / EC-max 22



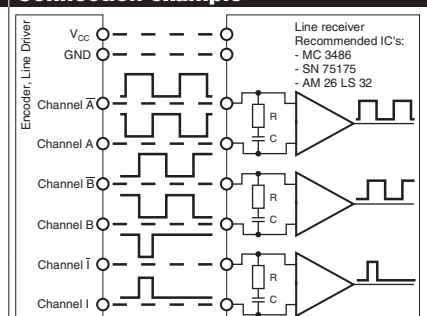
MR Encoder EC 16 / EC 22

- 1 N.C.
- 2  $V_{CC}$
- 3 GND
- 4 N.C.
- 5 Channel  $\bar{A}$
- 6 Channel A
- 7 Channel  $\bar{B}$
- 8 Channel B
- 9\* Channel I (Index)
- 10\* Channel I (Index)

DIN Connector 41651 flat band cable AWG 28 \*version with 3 channels

Pin assignment for RE-max see Page 260

## Connection example



Terminal resistance R = typical 120  $\Omega$   
Capacitor C  $\geq$  0.1 nF per m line length