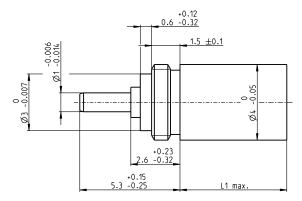
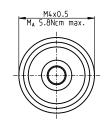
## Planetary Gearhead GP 4 C Ø4 mm, 0.002 - 0.015 Nm





Technical Data			
Planetary Gearhead		specia	I teeth
Output shaft	5	stainless	steel
Bearing at output		ball be	arings
Radial play, 5 mm from flange	1	max. 0.1	l4 mm
Axial play at axial load		max. 0	.2 mm
Max. permissible axial load			5 N
Max. permissible force for press fits	3		5 N
Sense of rotation, drive to output			=
Recommended input speed		< 4000	0 rpm
Recommended temperature range		-15	+80°C
Number of stages	2	3	4
Max. radial load,			
5 mm from flange	1.5 N	3 N	5 N

M 10:1

Stock program Standard program Special program (on request)			Order Number							
			416148	417408	420531					
Gearhead Data										
1	Reduction		17 : 1	68 : 1	280 : 1					
2	Reduction absolute		2025/	91125/	4100625/					
3	Max. motor shaft diameter	mm	0.6	0.6	0.6					
4	Number of stages		2	3	4					
5	Max. continuous torque	Nm	0.002	0.006	0.015					
6	Intermittently permissible torque at gear output	Nm	0.003	0.008	0.020					
7	Max. efficiency	%	76	70	65					
8	Weight	g	t.b.d.	t.b.d.	t.b.d.					
9	Average backlash no load	0	3.9	4.2	4.5					
10	Mass inertia	gcm <sup>2</sup>	t.b.d.	t.b.d.	t.b.d.					
11	Gearhead length L1	mm	5.7	7.4	9.2					





maxon Modular System											
+ Motor	Page	+ Sensor/Brake	Page	Overall lengtl	Overall length [mm] = Motor length + gearhead length + (sensor / brake) + assembly parts						
EC 4, 0.5 W, A	4			24.8	26.5	28.3					
EC 4, 0.5 W, B	4			23.3	25.0	26.8					
EC 4, 1 W, A	5			31.9	33.6	35.4					
EC 4, 1 W, B	5			30.2	31.9	33.7					

## Control electronics for sample units.

For fast, easy and affordable commissioning of the EC 4 drive, we recommend the use of standard production electronic units. We offer two versions for motors with and without Hall sensors.

